

The particle kinetic energy varies as

$$\frac{\partial}{\partial t} \frac{1}{2} \rho v^2 = \delta \mathbf{v} \cdot \mathbf{E} = \mathbf{j} \cdot \mathbf{E}$$

which can be written

$$\frac{\partial}{\partial t} \left(\frac{1}{2} \rho v^2 + \frac{\mathbf{B}^2}{8\pi} \right) + \nabla \cdot \mathbf{P} = 0$$

with the electromagnetic energy flux given by \mathbf{P} .

Note that, if initially each particle is represented by a localized spike in ρ and δ , it is an easy matter to average over a local volume V because the equations are all linear in ρ and δ .

Note that if $\mathbf{E} = -\mathbf{v} \times \mathbf{B} / c$

$$\text{then } \mathbf{P} = \mathbf{v}_{\perp} \frac{B^2}{4\pi}$$

Where \mathbf{v}_{\perp} is the velocity $\perp \mathbf{B}$

Note that \mathbf{E} plays no significant dynamical role.

$$\frac{E^2}{8\pi} = O\left(\frac{v^2}{c^2}\right) \frac{B^2}{8\pi}$$

Note, too, that the existence of \mathbf{E} depends upon what frame of reference the calculation uses.

See example in V. Vasyliunas, 2001, Geophys. Res. Letters, **28**, 2177.

Similarly \mathbf{j} plays no dynamical role because it has no energy and no strength.

Note that in any real gaseous medium \mathbf{j} is driven by a weak \mathbf{E}' , pulling energy out of the magnetic field.

B causes **j**, not vice versa.

Note that \mathbf{j} is driven by the relation

$$\frac{\partial \mathbf{E}}{\partial t} = c \nabla \times \mathbf{B} - 4\pi \mathbf{j}$$

Note, too, that $\frac{E'}{B} \sim \frac{c}{4\pi l \sigma} \sim \frac{10^{-4}}{l}$ at 10^4 K .

To estimate E' / B in specific cases, note that

$$\sigma \approx 2 \times 10^7 T^{3/2} \text{ sec}^{-1}.$$

So in a magnetic field B with characteristic scale l we have

$$\frac{E'}{B} \approx \frac{10^{-4}}{l} \left(\frac{10^4}{T} \right)^{3/2}.$$

For T not less than 10^4 K and l as small as 100 km, it follows that

$$\frac{E'}{B} \leq 10^{-11}.$$

The stress and energy in the electric field is no more than 10^{-22} times the energy and stress in the magnetic field.

Note that the dynamics is all in terms of

$$\rho = NM, \quad \mathbf{p} = NkT, \quad \mathbf{v}, \quad \text{and } \mathbf{B}$$

when $\mathbf{E} = -\mathbf{v} \times \mathbf{B} / c$.

\mathbf{E} and \mathbf{j} are secondary passive quantities.

Consider the role of the neglected \mathbf{E}' .

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{B}) - c \nabla \times \mathbf{E}'$$

For a collision dominated plasma, $\mathbf{j} = \sigma \mathbf{E}'$.

Hence $\mathbf{E}' = \frac{c}{4\pi\sigma} \nabla \times \mathbf{B}$ and

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{B}) - \nabla \times (\eta \nabla \times \mathbf{B})$$

$$\eta = \frac{c^2}{4\pi\sigma} \sim 0.5 \times 10^{13} / T^{\frac{3}{2}} \text{ cm}^3/\text{sec}$$

Magnetic Reynolds number

$$N_R = \frac{vL}{\eta}$$

For large N_R the principal effect is bulk transport of \mathbf{B} .

For a partially ionized gas

N = number density of neutral atoms,
 n = number density of ions/electrons

\mathbf{v} = mean bulk velocity of neutral gas

\mathbf{w} = mean bulk velocity of ions

\mathbf{u} = mean bulk velocity of electrons

τ_i = ion-neutral collision time

τ_e = electron-neutral collision time

τ = ion-electron collision time

p = pressure of neutral gas

$$NM \frac{d\mathbf{v}}{dt} = -\nabla p + \frac{nM(\mathbf{w} - \mathbf{v})}{\tau_i} + \frac{nm(\mathbf{u} - \mathbf{v})}{\tau_e}$$

Consider a slightly ionized gas, $n \ll N$.

Neglect ion and electron pressures.

$$m \frac{d\mathbf{u}}{dt} = -e \left(\mathbf{E} + \frac{\mathbf{u} \times \mathbf{B}}{c} \right) - \frac{m(\mathbf{u} - \mathbf{v})}{\tau_e} - \frac{m(\mathbf{u} - \mathbf{w})}{\tau}$$

$$M \frac{d\mathbf{w}}{dt} = +e \left(\mathbf{E} + \frac{\mathbf{w} \times \mathbf{B}}{c} \right) - \frac{m(\mathbf{w} - \mathbf{v})}{\tau_i} + \frac{m(\mathbf{u} - \mathbf{w})}{\tau}$$

$$\mathbf{j} = ne(\mathbf{w} - \mathbf{u})$$

From Ampere's law

$$\mathbf{u} = \mathbf{w} - \frac{c}{4\pi ne} \nabla \times \mathbf{B}$$

Neglect the electron and ion inertia. The sum of the two eqns. of motion gives

$$\frac{nM(\mathbf{w} - \mathbf{v})}{\tau_i} + \frac{nm(\mathbf{u} - \mathbf{v})}{\tau_e} = en(\mathbf{w} - \mathbf{u}) \times \frac{\mathbf{B}}{c}$$

$$= \mathbf{j} \times \mathbf{B} / c = \frac{(\nabla \times \mathbf{B}) \times \mathbf{B}}{4\pi}$$

Hence, for the neutral atoms

$$NM \frac{d\mathbf{v}}{dt} = -\nabla p + \frac{(\nabla \times \mathbf{B}) \times \mathbf{B}}{4\pi}$$

which is the usual MHD momentum eqn.

Note that

$$\mathbf{w} = \mathbf{v} + \frac{(\nabla \times \mathbf{B}) \times \mathbf{B}}{4\pi n Q} + \frac{cm/\tau_e}{4\pi ne Q} \nabla \times \mathbf{B}$$

$$\mathbf{u} = \mathbf{v} + \frac{(\nabla \times \mathbf{B}) \times \mathbf{B}}{4\pi n Q} - \frac{cM/\tau_i}{4\pi ne Q} \nabla \times \mathbf{B}$$

where

$$Q \equiv \frac{M}{\tau_i} + \frac{m}{\tau_e} \cong \frac{M}{\tau_i}$$

Then

$$\begin{aligned} \mathbf{E} = & -\frac{\mathbf{v} \times \mathbf{B}}{c} - \frac{[(\nabla \times \mathbf{B}) \times \mathbf{B}] \times \mathbf{B}}{4\pi nc Q} + \frac{M/\tau_i - m/\tau_e}{4\pi ne Q} (\nabla \times \mathbf{B}) \times \mathbf{B} \\ & + \frac{c}{4\pi ne^2} \left[\frac{(M/\tau_i)(m/\tau_e)}{Q} + \frac{m}{\tau} \right] \nabla \times \mathbf{B} \end{aligned}$$

Define

$$\alpha \equiv \frac{cB}{4\pi ne} \left[\frac{M/\tau_i - m/\tau_e}{M/\tau_i + m/\tau_e} \right]$$

Hall coefficient

$$\beta \equiv \frac{B^2}{4\pi n Q}$$

Pedersen coefficient

$$\eta \equiv \frac{c^2}{4\pi ne^2} \left[\frac{(M/\tau_i)(m/\tau_e)}{M/\tau_i + m/\tau_e} + \frac{m}{\tau} \right]$$

Ohm's coefficient

Write $\mathbf{b} = \mathbf{B}/B$, so that

$$\mathbf{E} = \frac{B}{c} [-\mathbf{v} \times \mathbf{b} - \beta[(\nabla \times \mathbf{b}) \times \mathbf{b}] \times \mathbf{b} + \alpha(\nabla \times \mathbf{b}) \times \mathbf{b} + \eta \nabla \times \mathbf{b}]$$

$$\mathbf{E}' = \frac{B}{c} [\eta \nabla \times \mathbf{b} + \alpha(\nabla \times \mathbf{b}) \times \mathbf{b} - \beta[(\nabla \times \mathbf{b}) \times \mathbf{b}] \times \mathbf{b}]$$

The induction equation

$$\partial \mathbf{B} / \partial t = -c \nabla \times \mathbf{E}$$

becomes

$$\frac{\partial \mathbf{b}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{b}) - \nabla \times (\eta \nabla \times \mathbf{b}) + \nabla \times \{ \beta[(\nabla \times \mathbf{b}) \times \mathbf{b}] \times \mathbf{b} - \alpha(\nabla \times \mathbf{b}) \times \mathbf{b} \}$$

This is the usual MHD eqn. with two extra terms.

In terms of the non-dimensional Lorentz force

$$\mathbf{f} = \frac{(\nabla \times \mathbf{b}) \times \mathbf{b}}{4\pi}$$

$$\frac{\partial \mathbf{b}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{b}) - \nabla \times (\eta \nabla \times \mathbf{b}) + \nabla \times [\beta \mathbf{f} \times \mathbf{b} - \alpha \mathbf{f}]$$

The magnetic energy equation can be written

$$\begin{aligned} \frac{\partial}{\partial t} \left(\frac{1}{8\pi} \mathbf{b}^2 \right) + \nabla \cdot \left[\frac{v_{\perp} \mathbf{b}^2}{4\pi} + \eta \mathbf{f} + \beta \mathbf{b}^2 \mathbf{f} + \alpha \mathbf{f} \times \mathbf{b} \right] \\ = -\mathbf{v} \cdot \mathbf{f} - \frac{\eta (\nabla \times \mathbf{b})^2}{4\pi} - 4\pi \beta \mathbf{f}^2 \end{aligned}$$

The right hand side represents the dissipation of magnetic energy. The term in square brackets represents the transport of magnetic energy.

Consider the Hall effect with $\beta = \eta = \nabla \alpha = 0$

$$\frac{\partial \mathbf{b}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{b}) - 4\pi \alpha \nabla \times \mathbf{f}$$

$$\frac{\partial \mathbf{v}}{\partial t} + \boldsymbol{\omega} \times \mathbf{v} = -\frac{\nabla p}{NM} - \nabla \left(\frac{1}{2} v^2 \right) + 4\pi C^2 \mathbf{f}$$

$$C^2 = B^2 / (4\pi NM), \quad \boldsymbol{\omega} = \nabla \times \mathbf{v}$$

Then

$$\frac{\partial \boldsymbol{\omega}}{\partial t} = \nabla \times (\mathbf{v} \times \boldsymbol{\omega}) + 4\pi C^2 \nabla \times \mathbf{f}$$

Hence

$$\frac{\partial}{\partial t} \left(\mathbf{b} + \frac{\alpha}{C^2} \boldsymbol{\omega} \right) = \nabla \times \left[\mathbf{v} \times \left(\mathbf{b} + \frac{\alpha}{C^2} \boldsymbol{\omega} \right) \right]$$

Note that the Hall (vorticity) contribution is smaller $O(1/L)$ compared to the magnetic field. And that makes it the same order as resistive diffusion.

$$\frac{\alpha}{\eta} \sim \Omega_e \tau_e \quad \Omega_e = \frac{eB}{mc}$$

The Hall effect is a small-scale effect.

See JGR, **101**, 10587-10625, (1996).

If the ion and electron pressures, inertia, and other applied forces \mathbf{L}_i , \mathbf{L}_e per unit mass are included, then

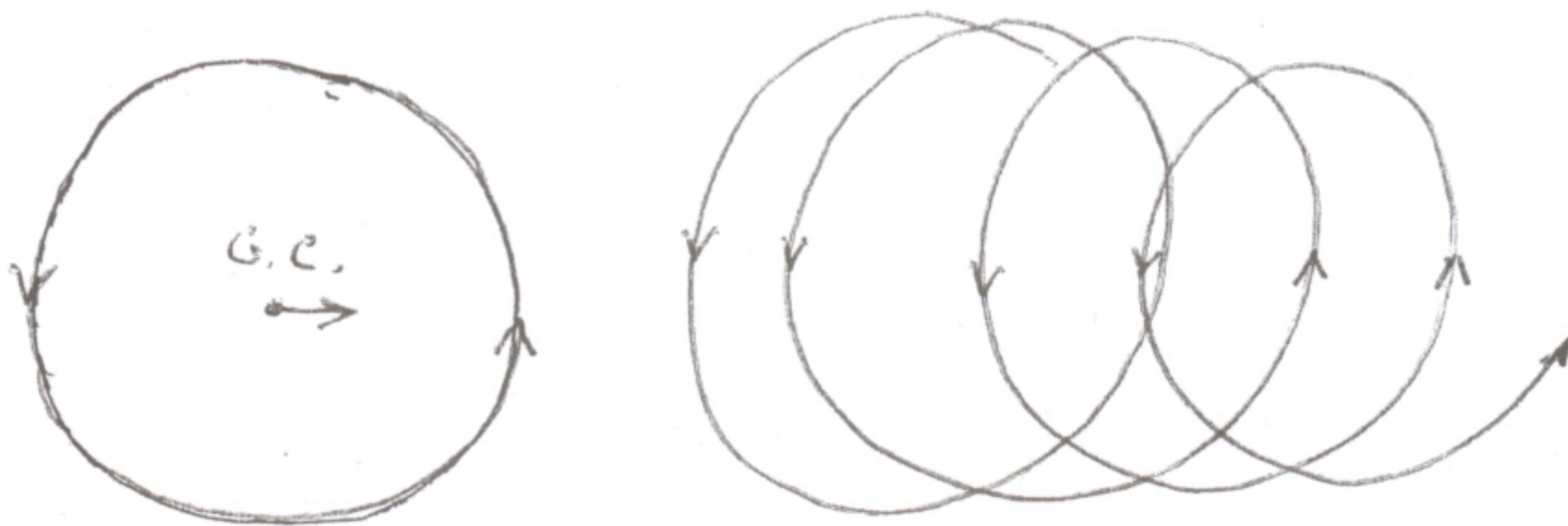
$$\begin{aligned} \frac{\partial \mathbf{b}}{\partial t} = & \nabla \times (\mathbf{v} \times \mathbf{b}) - \nabla \times [\eta \nabla \times \mathbf{b} - \beta \mathbf{f} \times \mathbf{b} + \alpha \mathbf{f}] \\ & - \frac{cm/\tau_e}{eBQ} \nabla \times \left[\frac{\nabla p_i}{n} + M \left(\frac{d\mathbf{w}}{dt} - \mathbf{L}_i \right) \right] \\ & + \frac{cM/\tau_i}{eBQ} \nabla \times \left[\frac{\nabla p_e}{n} + m \left(\frac{d\mathbf{u}}{dt} - \mathbf{L}_e \right) \right] \\ & - \frac{1}{Q} \nabla \times \left\{ \left[\frac{\nabla(p_i + p_e)}{n} + M \left(\frac{d\mathbf{w}}{dt} - \mathbf{L}_i \right) + m \left(\frac{d\mathbf{u}}{dt} - \mathbf{L}_e \right) \right] \times \mathbf{b} \right\} \end{aligned}$$

These extra terms include thermo-electric effects, the Biermann battery, the Eddington-Sweet effect, etc. which are all negligible under ordinary large-scale circumstances in astrophysical settings. But watch out for the small scales arising in tangential discontinuities, rapid reconnection, etc.

Compatibility of Newton and Maxwell

Consider a collisionless plasma, made up of equal numbers of electrons and singly charged ions.

Calculate the electron and ion motions using the guiding center approximation.



Write $\mathbf{u} = c \frac{\mathbf{E} \times \mathbf{B}}{B^2},$

$\mathbf{E} = -\frac{\mathbf{u} \times \mathbf{B}}{c}$

The motion of the guiding center is

$$\mathbf{v} = \mathbf{u} + \frac{\frac{1}{2} M \mathbf{w}_\perp^2 c}{e B^4} \mathbf{B} \times \nabla \frac{1}{2} B^2 + \frac{M w_\parallel^2 c}{e B^4} \mathbf{B} \times [(\mathbf{B} \cdot \nabla) \mathbf{B}]$$

Note that

$$\left(\frac{d\mathbf{v}}{dt} \right)_\parallel = -\frac{\mathbf{w}_\perp^2}{2 B^4} \mathbf{B} \cdot [(\mathbf{B} \cdot \nabla) \mathbf{B}]$$

Define

$$p_\perp = \sum_1 \frac{1}{2} M w_\perp^2, \quad p_\parallel = \sum_1 M w_\parallel^2.$$

The current density is

$$\mathbf{j}_\perp = \frac{c}{B^2} \mathbf{B} \times \left\{ \nabla p_\perp - \left[\frac{p_\parallel - p_\perp}{B^2} \right] (\mathbf{B} \cdot \nabla) \mathbf{B} + \text{NM} \frac{d\mathbf{u}}{dt} \right\}$$

and Ampere's law becomes

$$\text{NM} \frac{d\mathbf{u}}{dt} = -\nabla_\perp \left(p_\perp + \frac{B^2}{8\pi} \right) + \frac{[(\mathbf{B} \cdot \nabla) \mathbf{B}]_\perp}{4\pi} \left\{ 1 + \frac{p_\perp - p_\parallel}{B^2 / 4\pi} \right\}$$

So Ampere's law is automatically satisfied if the bulk velocity \mathbf{u} satisfies Newton's equation.

See Phys. Rev. **107**, 924 (1957).

Chew-Goldberger-Low Approximation

Let L denote scale of plasma and field in the direction along the field. There are, then, four invariants.

$$Lw_{\parallel} = \text{constant}$$

$$AB = \text{constant}$$

$$ALN = \text{constant}$$

$$w_{\perp}^2/B = \text{constant}$$

where A is the characteristic cross section of a flux bundle and B the field.

So

$$\frac{d}{dt} \left(\frac{p_{\perp}}{NB} \right) = 0, \quad \frac{d}{dt} \left(\frac{p_{\parallel} B}{N^3} \right) = 0$$

$$\frac{dp_{\perp}}{dt} = p_{\perp} \frac{d \ln NB}{dt} + \frac{p_{\parallel} - p_{\perp}}{\tau}$$

$$\frac{dp_{\parallel}}{dt} = p_{\parallel} \frac{d \ln (N^3/B)}{dt} - \frac{p_{\parallel} - p_{\perp}}{\tau}$$

ELECTRIC CIRCUIT ANALOG

It is asserted that the electric currents required by Ampere's law are subject to the familiar electric circuit equations.

MHD is equivalent to a Laboratory Electric Circuit.

However, in the laboratory circuit:

- (a) Current paths have fixed connectivity.
- (b) Current paths are fixed in the lab frame.

Whereas in MHD:

- (a) Current paths and connections vary according to the dictates of Ampere's law,

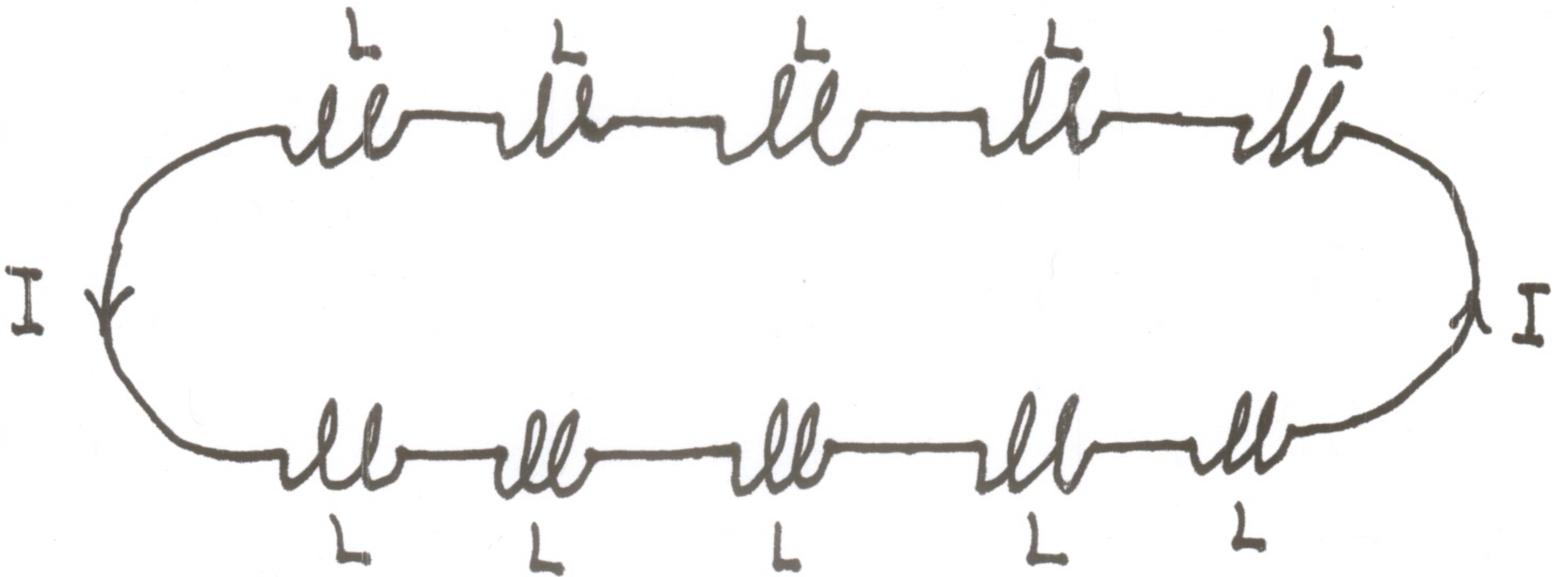
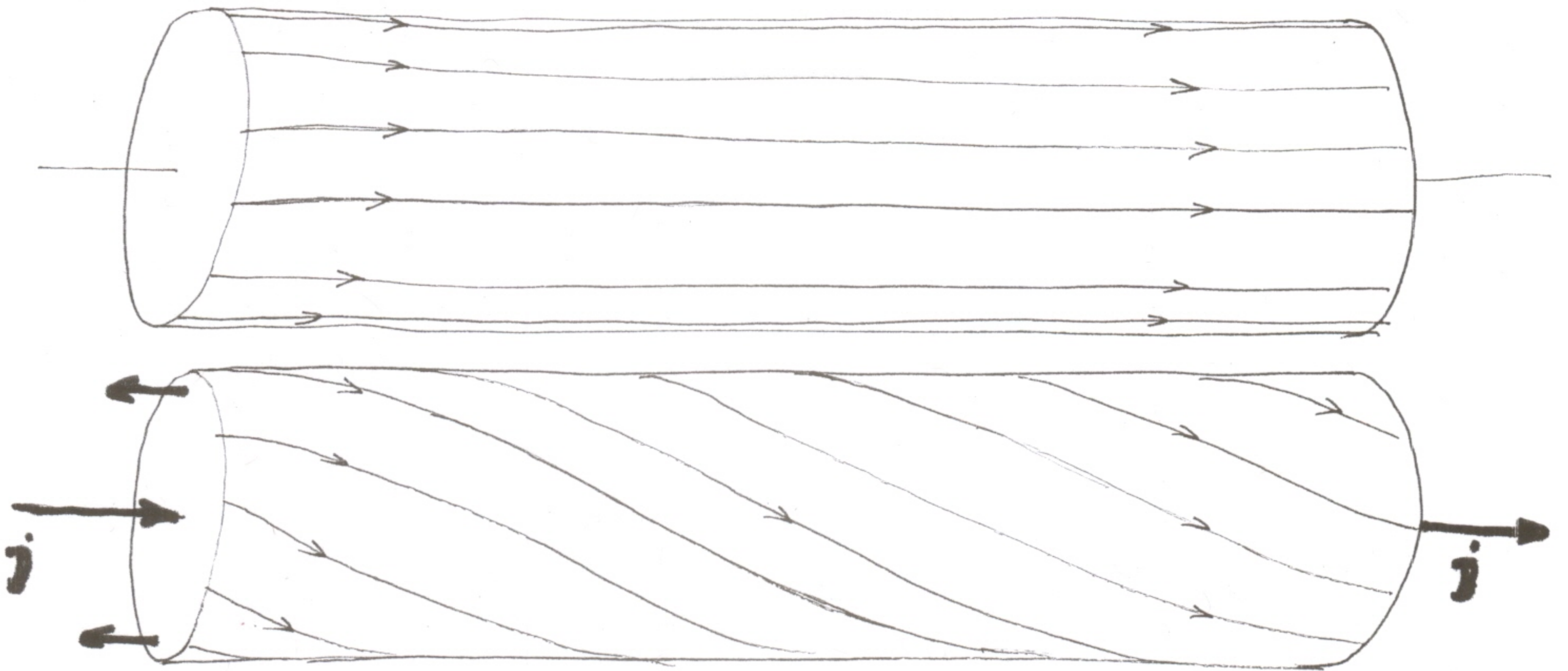
$$4\pi\mathbf{j} = c\nabla \times \mathbf{B},$$

as the swirling fluid velocity \mathbf{v} deforms \mathbf{B} ,

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{B}).$$

- (b) The current flows in the moving frame of reference of \mathbf{v} , in which $\mathbf{E}' = 0$, so there are no inductive *emf*'s applied to \mathbf{j} .

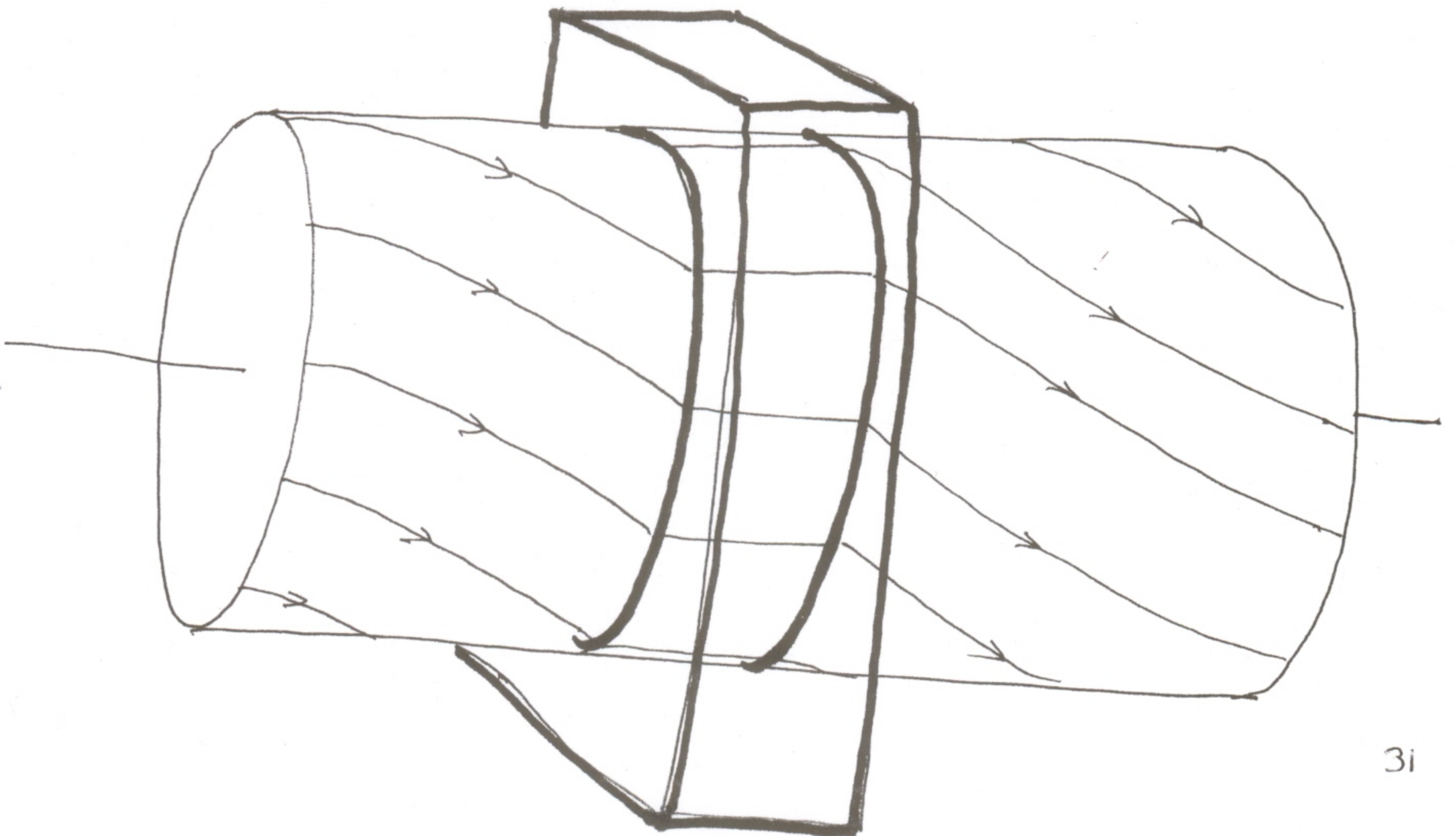
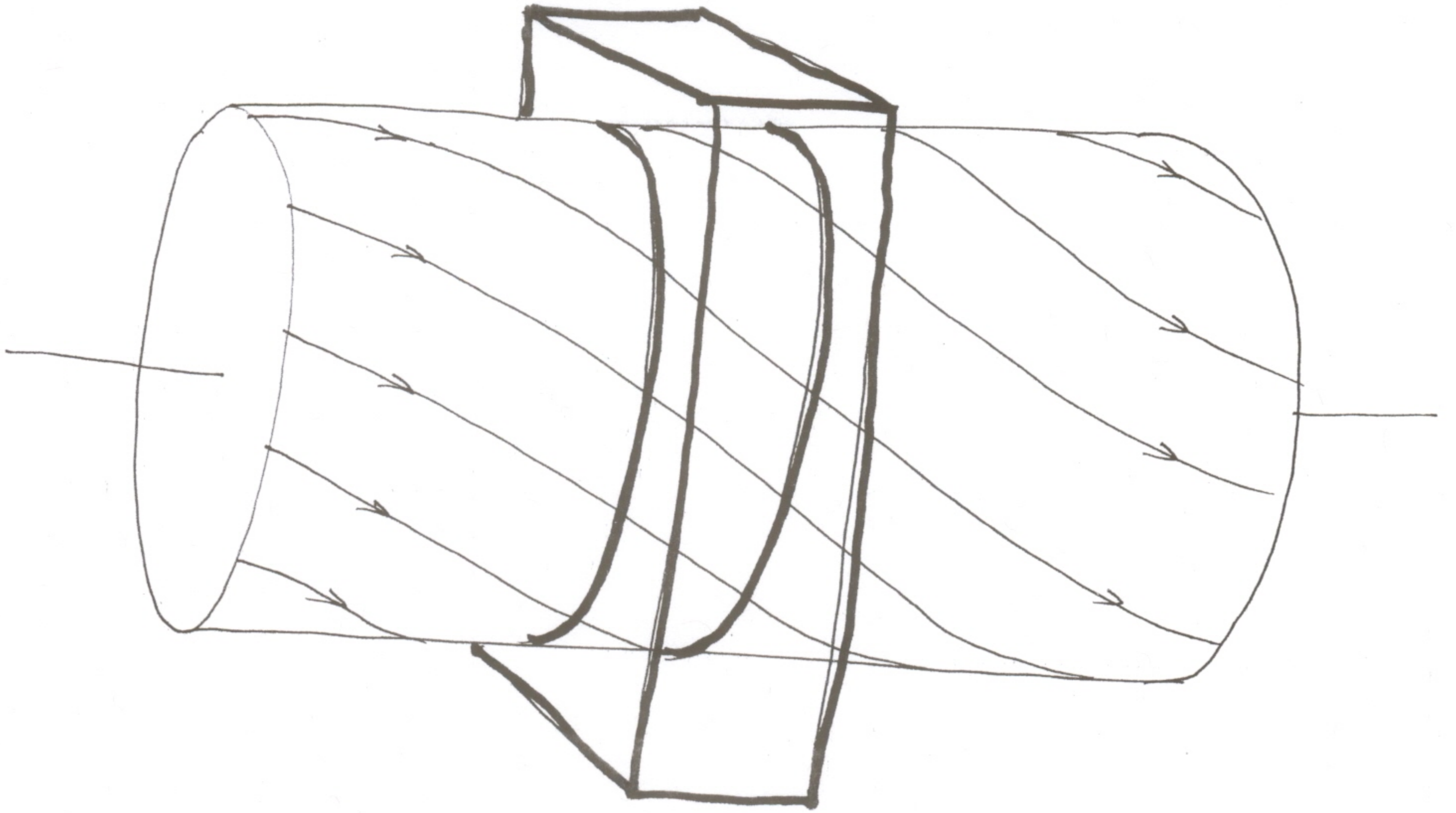
There is no electric circuit analog in time-dependent MHD.

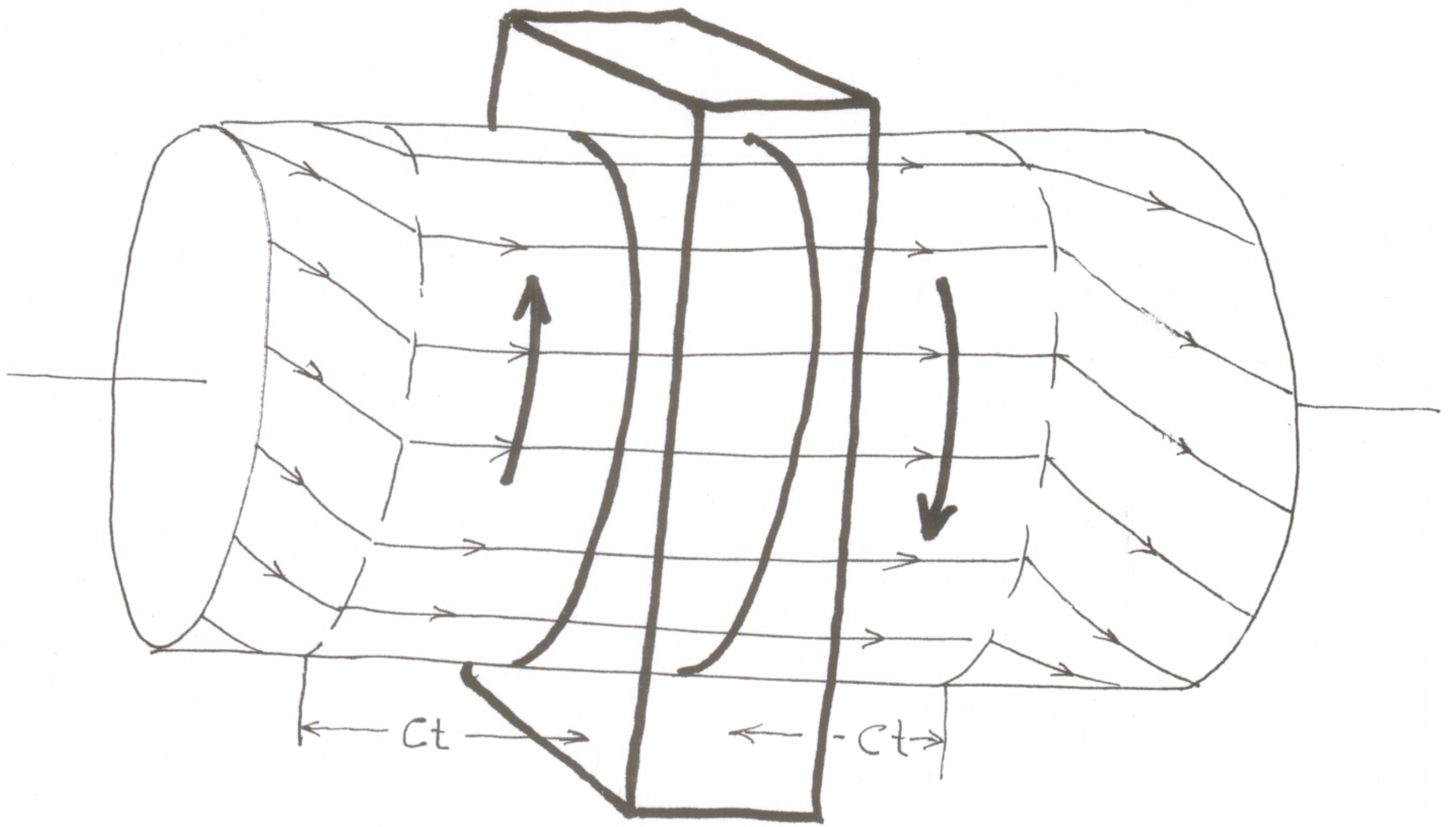


$I =$ Total current

$L =$ Inductance per unit length

$\frac{1}{2}LI^2 =$ Magnetic energy per unit length





(c)